



# LaunchPad

## Overview

The AB Dynamics LaunchPad is a compact powered platform designed to carry Vulnerable Road User (VRU) targets for ADAS development and testing. With a maximum speed of 50km/h and full path-following capability, it can be used with pedestrian, cyclist and moped dummies. Using AB Dynamics' advanced Synchro capabilities allows its motion to be precisely synchronised with the test vehicle and other ADAS targets.



#### Features

- Compatible with a range of official Euro NCAP VRU targets
- Self-propelled path-following platform for total test flexibility
- 4-wheel-drive 4-wheel-steer for ultimate manoeuvrability
- Onboard D-GPS motion pack and Synchro system
- Rapid Battery Swap system via side ramps no need to remove the target
- Ultra low-profile (65mm)\* and shallow sloping sides for low radar return and smooth over-run
- Same familiar software as other AB Dynamics products



Cyclist attachment





Adult dummy

Child dummy

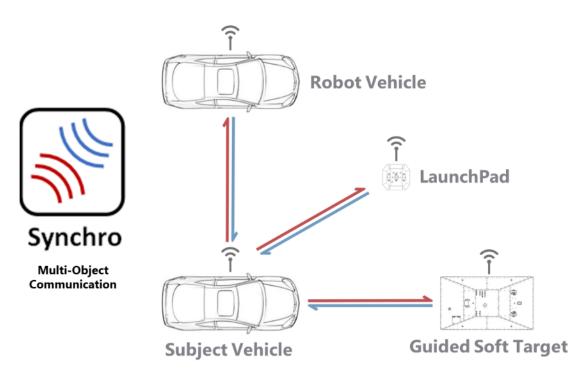
# Specifications

	LAUNCHPAD	LAUNCHPAD WITH HEAVY DUTY TOP PANEL FITTED
Dimensions (mm)	917 x 875 x 65	917 x 875 x 75
Weight (approx.)	40kg	45kg
Weather resistance	Fully sealed electronics, waterproof to IP67	Fully sealed electronics, waterproof to IP67
Maximum speed	50km/h	50km/h
Max. longitudinal acceleration (braking)	4m/s <sup>2</sup>	3.5m/s <sup>2</sup>
Payload	Pedestrian, cyclist, moped, animal. Maximum 15kg	Pedestrian, cyclist, moped, animal. Maximum 15kg
Batteries	Twin high-capacity LiFePO4 battery packs, Rapid Battery Swap system	Twin high-capacity LiFePO4 battery packs, Rapid Battery Swap system
Driver-over capacity	1000kg per wheel	3550kg per wheel

# Software

## Includes AB Dynamics RC Software, path-following and Synchro interface

At the heart of the LaunchPad platform is a Power controller running AB Dynamics' industry-standard Robot Controller RC Software. An onboard TrackFi radio shares position data with other AB Dynamics controllers via the Synchro interface. Programming the trajectory of the Launchpad is simple thanks to the graphical path generation utility. Complex scenarios with multiple moving objects can be created and run quickly and easily.







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